Unsupervised spike sorting for large scale, high density multielectrode arrays

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Unsupervised Spike Sorting for Large-Scale, High-Density Multielectrode Arrays

Graphical Abstract

Highlights

- An automated spike sorting method for dense, large-scale recordings is presented
- Efficient data representation enables sorting of thousands of channels
- Automated unit selection through model-based quality control
- Conventional spike sorting frequently fails under non-optimal signal conditions

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In Brief

Data volume and complexity make spike sorting for large-scale extracellular recordings computationally extremely challenging. Hilgen et al. introduce a method enabling analysis of recordings with thousands of channels and provide tools for automated quality control and unit selection.

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Unsupervised Spike Sorting for Large-Scale, High-Density Multielectrode Arrays

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SUMMARY

We present a method for automated spike sorting for recordings with high-density, large-scale multielectrode arrays. Exploiting the dense sampling of single neurons by multiple electrodes, an efficient, low-dimensional representation of detected spikes consisting of estimated spatial spike locations and dominant spike shape features is exploited for fast and reliable clustering into single units. Millions of events can be sorted in minutes, and the method is parallelized and scales better than quadratically with the number of detected spikes. Performance is demonstrated using recordings with a 4,096-channel array and validated using anatomical imaging, optogenetic stimulation, and model-based quality control. A comparison with semi-automated, shape-based spike sorting exposes significant limitations of conventional methods. Our approach demonstrates that it is feasible to reliably isolate the activity of up to thousands of neurons and that dense, multi-channel probes substantially aid reliable spike sorting.

INTRODUCTION

Large-scale, dense probes and arrays and planar multielectrode arrays (MEAs) enable extracellular recordings of thousands of neurons simultaneously (Ballini et al., 2014; Berdondini et al., 2005; Eversmann et al., 2003; Frey et al., 2010; Hutzler et al., 2006; Maccione et al., 2014; Müller et al., 2015; Obien et al., 2015). Exploiting such data requires the reliable isolation of extracellularly recorded spikes generated by single neurons (spike sorting), a computationally costly task that is difficult to scale up to large numbers of recording channels (Rey et al., 2015). For conventional devices with up to tens of recording channels, a typical workflow consists of initial event detection, followed by semi-automated clustering based on spike waveform differences, followed by manual inspection and refinement. If the recording channels are sufficiently well separated, then there is no or little overlap between their signals, and spike sorting can be performed by clustering a low-dimensional representation of spike shapes (Harris et al., 2000; Lewicki, 1998; Quiroga et al., 2004).

This approach is inappropriate for dense, large-scale recordings. First, on dense MEAs, spike sorting becomes a complex assignment problem because not only multiple neurons contribute to the compound signal recorded on distinct channels, but individual spikes are also recorded by several neighboring channels simultaneously (Prentice et al., 2011; Rossant et al., 2016). Events are thus described by multiple waveforms and their locations, with an exponential number of potential assignments that can only be tackled using approximate algorithms. Second, the size of the datasets makes extensive manual intervention impractical; hence, as much of the process as possible, including quality control, should be automated.

Much of the variability in spike shapes is due to measuring them at different positions relative to the neuron. In conventional recordings, relatively small signals are measured using large electrodes averaging currents originating from different parts of the neuron. High-density MEAs with small electrodes detect primarily strong currents at the axon initial segment (AIS). The mechanism for generating action potentials is thus represented with a higher weight in the measured signals, leading to less variability in measured spike shapes. Existing solutions, demonstrated on data from hundreds of channels, are either template-matching methods (Marre et al., 2012; Prentice et al.,...
the removal of uninformative spike features to make fitting of a mixture model computationally feasible (Rossant et al., 2016).

Here we present a very fast and fully automated method for spike sorting. Dense sampling enabled us to obtain a rough estimate of a source location for each detected event (Muthmann et al., 2015), yielding dense, spatially separated clusters originating from single neurons, as demonstrated using optogenetic stimulation and confocal imaging. Average waveforms are obtained for each event, with noise reduced by signal interpolation. Shape features extracted from this waveform are then combined with spatial locations so that the clustering problem is reduced to finding local density peaks in few dimensions.

We demonstrate this method using light responses in the mouse retina and spontaneous activity in cell cultures recorded with a 4,096-channel MEA. A direct comparison with conventional spike sorting also exposes severe and hard to detect limitations of the latter. A parallelized implementation of this method that is capable of sorting millions of spikes within a few minutes on a fast workstation, as well as a tool for data visualization, can be downloaded at https://github.com/martinosorb/herding-spikes.

RESULTS

Spatial Spike Localization

Figure 1A illustrates a retinal whole-mount placed on the MEA. Spikes are detected using a threshold-based method that exploits dense sampling to improve detection performance and assigns each spike an estimated location based on the barycenter of the spatial signal profile (Muthmann et al., 2015). This procedure yields spatio-temporal event maps, where each event is identified by a time stamp, two spatial coordinates, and a single interpolated waveform. The resulting spatial activity maps provide a higher spatial resolution for spike locations than given by the electrode pitch (Figure 1B). Spikes were found in dense clusters surrounded by areas of low event density. The relationship between recorded signals and spike locations is illustrated in Figure 1C, where estimated spike locations are shown together with corresponding raw data segments from nearby electrodes. The examples show how spike locations relate to the spatial decay of the voltage peaks and that the decay was sufficiently wide to estimate their peak locations (Figure 1D; Petersen and Einevoll; 2008; Lindén et al., 2011; Mechler et al., 2011). Thus, on dense MEAs, event locations provide a compact summary of the spatial activity footprint for each spike. Inspecting waveforms, however, reveals the presence of multiple units in small areas (Figure 1E), demonstrating that clustering spatial locations alone is insufficient for reliable single-unit isolation (Prentice et al., 2011).

Combined Spatial and Shape-Based Clustering

Next, spikes are clustered using a combination of their estimated locations and dominant waveform features, extracted via principal-component analysis (PCA), which provide a complementary, compact description of the events. The location estimate is an effective way of summarizing the spatial footprint each spike leaves on the array, whereas waveforms enable the separation of spatially overlapping sources, and they remove ambiguities at spatial cluster boundaries.
The mean shift algorithm was used for clustering, with the number of clusters automatically determined and controlled by a single scale parameter (Comaniciu and Meer, 2002). Clusters are formed by moving spikes along density gradients and augmented by local differences in spike waveforms. Including the first two principal components was sufficient to successfully isolate single units, reducing the high dimensional assignment problem to four-dimensional clustering, which can be performed in minutes for millions of events. In addition to the scale parameter, this method also requires a mixing coefficient for the shape information.

Figures 2A–2C show the result of clustering waveforms acquired at 24 kHz from 1,024 channels, yielding 440,000 spikes separated into 1,600 units. Cluster sizes ranged from tens of spikes to several thousands, corresponding to firing rates ranging from 0.1 to 30 Hz. In a magnified view, Figure 2B shows that units may indeed spatially overlap but are well separated by their waveform features. Overall, units with clearly bi-phasic and large-amplitude waveforms tend to form the more spatially coherent clusters, whereas smaller events are spatially more spread out.

Units with small waveforms originate from neurons with weak signals detected because of low thresholding during the
As a first assessment of the clustered units, we generated electrical images for individual units (Figure 2D). These images provide a spatio-temporal representation of the raw signal recorded around the time of spiking and is generated as a spike-triggered average of the signal on each electrode. Of 406 inspected units with at least 100 spikes, all but one had an estimated location within 40 μm of the electrode that contained the peak signal (median distance, 9.7 μm), indicating that units are indeed well aligned with their spatio-temporal electrical footprint. Furthermore, the recordings were of sufficient detail to isolate axonal propagation (Figure 2D), characterized by a separate, weak positive peak following by a negative peak traveling downward (toward the optic disk). Because these events peak within less than 100 μs of the main signal, they are not detected as separate events but, instead, introduce a small bias on the location estimates during spike localization.

We also tested our method on activity recorded from cultured hippocampal neurons. Figure 2E illustrates that isolation of single units is also feasible for these preparations, although here the spike localization was less precise than in the retina. We attribute this to a larger effective conductivity in the space above the electrodes, resulting in smaller signal amplitudes, which, in turn, increases the influence of noise on localization (Ness et al., 2015). Such conductivity is likely much lower for the 200- to 300-μm-thick retina, leading to larger and more precisely localizable signals. Ness et al. (2015) show that even small MEA-tissue gaps strongly reduce the signal amplitudes, a likely explanation for the clear, sharp boundaries between areas with and without recorded spikes. Nevertheless, spikes in cultures were typically spatially well clustered, and waveform differences had sufficient detail to allow separation of overlapping units (Figure 2E, right).

Validation with Optogenetics and Anatomical Imaging
To test whether the detected units indeed correspond to single neurons, we used Thy1-ChR2-YFP retinas (see Experimental Procedures) expressing Channelrhodopsin-2 (ChR2), a light-gated cation channel, under the Thy1 promoter in about half of all retinal ganglion cells (RGCs) (Raymond et al., 2008). This allowed us to stimulate spiking exclusively in a subset of visually identifiable RGCs to clearly establish correlates between single spike–sorted units and individual RGCs.

To quantify the separability of these distributions, we computed the area under the receiver operating characteristic (ROC) curves (AUC), constructed from the distributions of self-correlations and correlations with events in the nearest unit (Figure 3E) or all neighboring events (Figure 3F). The AUC was calculated as the integral of the area spanned by the probability of finding a self-correlation above a sliding threshold, as a function of the probability of finding a cross-correlation above this threshold (true positives versus false positives), so that a value of 1 corresponds to perfectly separated distributions, whereas 0 indicates full overlap.

The median AUC for all units increases with z before plateauing at values about $a = 0.4$ (Figure 3D), indicating that the combined features overall improved separation into single units. The AUC distributions show that this effect is substantial (Figures 3E and 3F). Although spatial clustering alone only yielded three (of 788 units with more than 100 spikes) units with AUC > 0.9 compared with events from its closest neighbor, this increases to 130 (of 956 units with more than 100 spikes) for $a = 0.32$. This number rapidly increases when $a = 0.25$ and plateaus for larger values, indicating that the precise choice of this parameter is not critical. It is important to note that, although high AUC values indicate well isolated units based on waveform features alone, units with a small AUC should not be rejected because they may still be spatially well isolated.

In summary, waveform features help both to refine existing units found by spatial clustering and to separate spatially overlapping units. Event locations and waveforms provide an effective complementary approach of summarizing the key features of the spatio-temporal footprint left by spikes on the array.
stimulation of ChR2-expressing RGCs. In addition, 77 units were significantly less active during light stimulation than during ChR2 stimulation, presumably reflecting neurons unresponsive to photoreceptor activation but nevertheless expressing ChR2. The responsiveness of each unit to ChR2 activation was assessed by determining the correlation of an individual unit’s...
activity with the overall population activity (Figure 4A, bottom). Almost all highly active units during ChR2 stimulation also showed higher correlation, with some exhibiting uncorrelated activity, which we attribute to intrinsic spontaneous activity that could not be blocked. Of all detected units, about 40% had a correlation larger than 40%, close to the expected fraction of Thy1-expressing RGCs.

Next we co-localized the activity with confocal micrographs of labeled neurons (Figure 4B). We analyzed an area of 0.78 mm², where 195 somata were manually annotated, and 211 units were detected. An example of the alignment of activity and anatomical image is shown in Figure 4B for activity obtained during photoreceptor stimulation (left) and ChR2 activation (right). All units with significant activity during ChR2 stimulation were closely co-localized with a labeled soma. Similarly, there is a tight co-localization between the neurons and electrical images generated from the raw traces (Figure 4C).

To verify whether labeled somata and localized units were significantly close to each other, we computed the distance to the closest soma for every unit. If units and somata were randomly distributed, the probability of a distance \( r \) would be \( 2 n \pi r^2 n^{-1} \), where \( n \) is the density of somata (Chandrasekhar, 1943). We compared the distribution of 198 distances to this null model using a one-tailed Kolmogorov-Smirnov test (Figure 4D), confirming that the distances are significantly smaller than predicted by the random model. To account for the effect of spontaneous activity, we applied the test after separating the units into two groups according to their activity level or population correlation, varying the threshold that separates the two sets. The locations of the less active and less correlated units are compatible with a random distribution, whereas the more active and better correlated units are significantly closer to their anatomical counterparts.

**Model-Based Validation and Quality Control**

As pointed out above, detection was performed with a low threshold to minimize false negatives. Hence some units are expected to contain ambiguities the clustering algorithm cannot fully resolve. For instance, the localization error is typically larger for spikes with small amplitudes (Muthmann et al., 2015); hence, it may not be possible to spatially cluster these events reliably.

To assess the cluster assignments’ quality and automatically reject poorly separated units, we followed an approach proposed by Hill et al. (2011). Under the assumption that spike locations and waveform features can be described by a multivariate normal distribution, a comparison of the clusters assignments with those predicted by a Gaussian mixture model provides an estimate of the classification performance. Each unit was investigated in turn, including all of its immediate neighbors, by fitting a six-dimensional Gaussian mixture model with the number of components equal to the number of units (Experimental Procedures). We included four PCA dimensions to ensure that the model best exploits all available waveform features while ensuring reliable convergence. To evaluate the relevance of spatial locations and waveform features for clustering, the model was also fit to each of these features separately.

The model comparison produces a confusion matrix with the estimated number of false positives and negatives for each unit, which is then summarized into a single measure (F-score). Two typical outcomes of this procedure are illustrated in Figures 5A and 5B for relatively crowded areas on the array. Figure 5A shows a unit with a distinct waveform (blue) and four neighbors...
within one electrode radius. The blue unit was already well isolated based on waveform features alone (PCA, F-score = 0.97) but not when only spike locations were considered (X/Y, F-score = 0.68). Combining locations and waveforms did not yield further improvement, although it helped to isolate its neighbors based on their spike locations.

Figure 5B shows five spatially well separated units with smaller and very similar waveforms. Waveform-based clustering alone gave poor results, but adding spike locations improved it considerably.

Figures 5C–5F summarizes the analysis performed on a 7.6-million spikes dataset. Each of 2,234 units with a spike rate of at least 0.3 Hz took, in turn, the role of the blue unit in Figure 5A, and all units within a radius of 42 μm were combined into mixture models. When location and waveform features were used for quality control, 55% of the units (1,230) had an F-score > 0.95 and 15% (334 units) an F-score > 0.99 (Figure 5C; X/Y+PCA). These fractions decreased only slightly when locations were used on their own but substantially for waveforms (PCA) alone. Comparing F-scores for waveforms or combined features shows that adding locations improved it considerably. Importantly, immediately adjacent neurons generally exhibit different responses, as expected from the mosaic functional organization of RGCs.

The fact that the majority of these units, even those with very small waveforms, exhibit reliable light responses demonstrates that the signal variance is mainly due to physiological causes rather than electrical noise (Muthmann et al., 2015). Units with well defined waveforms are typically also well separated in their PCA projections, whereas small waveforms are mainly clustered based on spatial locations (compare units 1–3 with units 5–7 in Figure 6C). The cluster F-scores (shown above the waveforms in Figure 6B) are lower for units with small waveforms; hence, further analysis for well isolated cells can rely on this measure.

Comparison with Conventional Spike Sorting

Conventional spike sorting relies on differences in spike waveforms. To evaluate how our approach scores in comparison with such methods, we compared our method with the outcome of manually curated spike sorting done on each MEA channel separately. Conventional spike sorting was performed using
T-distribution expectation-maximization (E-M) clustering (Shoham et al., 2003) followed by manual inspection and correction (Plexon Offline Sorter). The data used for this comparison were recorded at 24 kHz with 1,024 electrodes (Figure 1) and included 538 clusters with at least 200 spikes each. For each cluster, we located the most similar sorted unit using spike count cross-correlation following binning (each unit is typically found on multiple electrodes) and obtained the number of spikes in the sorted unit that were not part of the cluster (false negatives) and the number of spikes in the cluster not present in the sorted unit (false positives). As for the mixture model above, we then computed precision, recall, and the F-score for each cluster (Experimental Procedures).

Figure 7A illustrate two common cases we encountered. The first example shows an almost identical assignment for both methods that we found in 96 clusters (18%), with an F-score larger than 0.95 (Figure 7B). Such pairs had very few false positives and negatives (e.g., the pair in Figure 7A, top, had nine false negatives and no false positives of 1,818 spikes).

For many of the remaining clusters, the F-score was dominated by a sizable fraction of false negatives, spikes in the sorted unit that were not included in the corresponding cluster (units with low recall in Figure 7C). An inspection of the spatial locations of these events showed that false negatives were often located far away from the cluster centroid and visually appeared to be part of another unit (Figure 7A, center and bottom, orange events). Figure 7A, center and bottom, illustrates the consequences of erroneous assignment by conventional spike sorting, changing On cells into On-Off cells by merging spikes from other nearby Off cells.

We found that the inclusion of distant spikes happened frequently, with an average distance of false negatives from the cluster centroid typically around 30 μm (Figure 7D). This suggested that they were wrongly included in a sorted unit based on waveform similarities. To see whether these failures are associated with specific waveform features, we compared the F-scores with the average projections of the waveforms along their first principal component (Figure 7E). The PC1 projection provides an indicator of signal quality for each unit (Figure 2B), and, indeed, lower F-scores were observed almost exclusively for low-scoring units. Hence, we conclude that conventional spike sorting only allows reliably isolation of units with strong, very prominent waveform features, whereas smaller, less distinct
waveforms cannot be separated reliably on the exclusive basis of their shape.

**DISCUSSION**

Spike sorting is a critical step in the analysis of extracellular electrophysiological recordings. An erroneous assignment of spikes can have severe consequences for the interpretation of neural activity, which has motivated the development of joint models of spike waveforms and neural activity to avoid spurious or biased correlation estimates (Ventura and Gerkin, 2012). In high-density recordings, increasingly used both for in vitro and in vivo studies, assigning spikes to single units becomes exponentially complex as a function of the number of events; hence, it requires approximate solutions. Moreover, the sheer size of the data prevents detailed manual inspection and quality control.

Here we solve this task by creating an efficient, low-dimensional data representation, based on spatial spike locations and the most prominent waveform features, that can be clustered efficiently. We found that clustering in four dimensions, with two dimensions representing waveform features, was sufficient to achieve high performance, which we attribute to the fact that the signals reliably measured with a dense MEA mainly originate from strong currents at the AIS of each neuron, with limited variability between neurons. This enables estimating their spatial origin but limits variability to support shape-based spike sorting. Comparison of optogenetically evoked spikes with anatomical images indicates that detected spikes typically cluster near the AIS and that localization alone is sufficiently precise to reliably isolate some neurons even without using additional waveform features.

Our method could be used with arrays and probes where an event location estimate can be reliably obtained. The dimensionality of the clustering step can then be adjusted to exploit higher waveform variability. The complexity of the clustering algorithm scales quadratic with the number of spikes, and the highly optimized version used here has a better performance when prominent spatial clustering is present. We developed a parallelized implementation that allows sorting of millions of spikes in minutes (ten million spikes take about 8 min on a 12-core 2.6-GHz Xeon workstation). Together with a method for quality control, this makes it possible to perform parameter sweeps to identify the optimal parameters of the clustering algorithm. Clustering is followed by an automated assessment of clustering quality, allowing the automated rejection of poorly isolated units and manual inspection of borderline cases. We also provide a visualization tool where further annotation can be performed.

The complete workflow consists of event detection, spatial localization, clustering, quality control, and, finally, optional manual inspection. The former two currently constitute the main bottleneck. Detection takes about four times real time and scales linearly with recording duration. The complexity of the spike localization scales linearly with the number of detected events and runs roughly in real time for recordings with normal spike rates. For both methods, parallelized implementations are under development.

Our work with high-density recordings has revealed significant limitations of purely shape-based spike sorting for MEA recordings. It is virtually impossible to evaluate how many units are...
represents in a single electrode signal. If the electrode is positioned close to a neuronal cluster, one or two units with strong signals usually have sufficiently distinct waveforms to be separable. However, comparison with spike locations showed that weaker signals arising from more remote cells are generally not distinguishable based on shape alone. We frequently found cases where spikes of neurons with entirely different physiological signatures were mixed by shape-based sorting, a problem that cannot be avoided even by careful manual inspection. Our method, on the other hand, handles such situations much better because spatial location estimates are sufficiently precise to disambiguate borderline cases. Thus, a main factor affecting sorting performance is the noise and bias in spatial localization, both depending on signal quality (Muthmann et al., 2015).

A different strategy, outlined by Marre et al. (2012), is to estimate spatio-temporal templates that are then used to identify spikes from each neuron (Dragas et al., 2015). This shifts the computational burden from spatial interpolation and source localization in our method to the deconvolution of spikes from raw data. We found that adding shape criteria at the detection stage could lead to false negatives, suggesting that templates can only be reliably estimated for neurons with sufficiently high firing rates. A third method, recently developed by Rossant et al. (2016) for high-density in vivo probes, reduces complexity by masking irrelevant parts of the data based on geometric constraints before fitting a mixture model and clustering the data. This avoids an early discarding of potentially useful information, which our method does by using signal interpolation and Marre et al. (2012) did by creating templates. On the other hand, although potentially more precise, this method is computationally more demanding and, hence, more suitable for data from hundreds of channels.

**EXPERIMENTAL PROCEDURES**

**Electrophysiology**

Experimental procedures were approved and carried out in accordance with the guidance provided by the United Kingdom Home Office, Animals (Scientific Procedures) Act 1986 (Retinal Recordings), by the institutional Istituto Italiano di Tecnologia (IIT) Ethic Committee, and by the Italian Ministry of Health and Animal Care (Authorization ID 227, Prot. 4127 March 25, 2008) (neural cultures; Panas et al., 2015).

Experiments on the retina were performed on adult wild-type mice (C57BL/6, aged post-natal days [P] 27–39) or on B6.Cg-Tg(Thy1-COP4/3Brain) strain (Thy1-ChR2-YFP; The Jackson Laboratory; RRID:IMSR_JAX:007615) aged P69–96. Recordings from the RGC layer were performed using the BioCam4096 platform with active pixel sensor (APS) MEA chips (type BioChip 4096S, 3Brain), providing 4,096 square microelectrodes (21 μm × 21 μm) on an active area of 2.67 mm × 2.67 mm, aligned in a square grid with 42 μm spacing. The platform records at a sampling rate of about 7 kHz/ electrode when measuring from the full 64 MEA, but sampling rate decreases to 24 kHz when recording from 1,024 electrodes. Raw data were baseline-subtracted and inverted, and then the center of mass was determined. To filter out noise and poorly detected neurons in recordings at 7 kHz, we developed an automated post hoc event rejection. To this end, noise events were sampled from areas on the MEA where no activity was recorded, such as at incisions or uncovered areas (identifiable by low spike counts). Up to 1,000 of such events and up to 1,000 events with large amplitudes were used to train a support vector machine with radial basis functions. This model was then used to classify events as true spikes or noise (Figure S1).

**Spike Detection, Localization, and Selection**

The procedures for spike detection and localization are described in detail elsewhere (Muthmann et al., 2015). Weighted interpolated signals were generated using two spatial templates to capture both spikes originating close to or between electrodes. The running baseline and noise estimate were computed as signal percentiles, and putative spikes were detected as threshold crossings. This procedure ensures detection of temporally overlapping spikes as long as they leave a distinct spatial footprint. Next, source locations were estimated for each event by considering the spatial spread over neighboring electrodes. The signals were baseline-subtracted and inverted, and then the median signal was subtracted to minimize bias because of noise. The signal was clipped to positive values, and the center of mass was determined. To filter out noise and poorly detected neurons in recordings at 7 kHz, we developed an automated post hoc event rejection. To this end, noise events were sampled from areas on the MEA where no activity was recorded, such as at incisions or uncovered areas (identifiable by low spike counts). Up to 1,000 such events and up to 1,000 events with large amplitudes were used to train a support vector machine with radial basis functions. This model was then used to classify events as true spikes or noise (Figure S1).

**Spike Sorting**

Data points were clustered using an implementation of the mean shift algorithm (Comaniciu and Meer, 2002), available in the scikit-learn open source machine learning library (Pedregosa et al., 2011). Importantly, this algorithm does not require prior knowledge of the desired number of clusters. It depends on a single parameter, the bandwidth $h$, which determines the expected cluster size, which, in turn, can be estimated from a typical spatial cluster size in an activity plot (Figure 1B) and was here set to $1.26 \mu m$ (the average width of clusters). The clustering process was run on a four-dimensional space consisting of two dimensions, indicating the location of each event on the chip, $x$ and $y$, and two dimensions representing the first two principal components of the event’s waveform. The latter were multiplied by an additional dimensional constant $\alpha$ that tuned the relative importance of the waveform components compared with the spatial coordinates. To parallelize this algorithm, we exploited the fact that all points follow a local density gradient until they converge to a local maximum, the center of a cluster. Because every data point does so independently of the others, this process is run in parallel, which improved performance roughly proportionally to the number of available central processing units (CPUs). The relevant code has been merged into the scikit-learn Python library.

**Quality Metric**

Following Hill et al. (2011), we fitted a multivariate Gaussian mixture model to a set of $K$ clusters and then estimated their overlap using posterior probabilities to obtain the probability of incorrect assignments under the assumption of a Gaussian cluster shape. The model is fit in six dimensions, with the two spatial coordinates and the projections of the spike waveform along the first four principal components. For each cluster, we assume that only spikes in nearby clusters interfere with the sorting. Therefore, all clusters or spikes within a radius of $42 \mu m$ (electrode pitch) are included in the model. To obtain meaningful fits for sets of clusters with very disparate number of spikes, a Gaussian is fit...
to each cluster individually before combining them into a mixture model. The assignment quality is evaluated as follows. Let the probability of spikes $s$ in cluster $c$ be $P(C = c | S = s)$; the estimated fraction of spikes in cluster $k$ that could belong to cluster $i$ is given by $P^k_i = (1/N_k) \sum_{c} P(C = i | S = s)$; by generalizing to all other clusters, we obtained the number of false positives in $k$:

$$f^k_i = \sum_{c \neq s} P^k_i = \sum_{c \neq s} \frac{P(C = k | S = s)}{P(C = i | S = s)}.$$

Correspondingly, the number of false negatives, the fraction of spikes in cluster $c$ that was expected to be assigned to other (i.e., wrong) clusters, was obtained as $f^c_i = \sum_{k \neq s} P(C = k | S = s)$.

The probabilities $P(C = c | S = s)$ were given by mixture model. To obtain a single quality measure, we compute ($P_k$) and recall ($R_k$):

$$P_k = \frac{C_k - f^k_k}{C_k},$$

$$R_k = \frac{C_k - f^k_k}{f^c_k}.$$

The harmonic mean of these quantities yields the F-score:

$$F_k = \frac{2P_k R_k}{P_k + R_k}.$$

Confocal Imaging and Image Analysis

To achieve a precise alignment of RGCs with recording electrodes, the retina was fixed with 4% paraformaldehyde (in 0.1 M PBS and 200 mM sucrose) on the MEA chip for 1 hr after recording. We have determined that tissue shrinkage, which may interfere with activity alignment, is negligible for this protocol. The retina was rinsed several times with 0.1 M PBS, embedded with Vectashield (Vector Laboratories), and sealed with a coverslip (Menzel Glaaser). Imaging was performed with a Leica SP5 confocal upright microscope equipped with a 25×/0.95 numerical aperture (NA) working distance (WD) 2.5 mm water immersion objective for optimal signal collection focusing on areas encompassing 8×8700×300μm field of view. In each field, images (2,048× 2,048 pixels) were acquired in z stacks in tissue thickness of 60–100 μm (optical slicing yielding 30–50 image planes). A lateral resolution of 200 nm per pixel, just above the diffraction limit, and optical slicing of 550 nm provided an adequate trade-off between sufficient image details and acquisition time, minimizing the risk of photo damage. For image restoration, the Richardson-Lucy method (Lucy, 1974; Richardson, 1972) was used. In addition to the fluorescence signals in specific fields, large-field images, including images of the MEA, were acquired to enable co-localization of images with RGC spiking activity.

In one Thy1 YFP-ChR2 retina, RGC somata were manually annotated in selected subfields where activity was recorded, and the confocal images of the RGC layer were spatially aligned with the estimated locations of detected events. To this end, the active area of one electrode was determined, and the remaining electrode locations were computed, generating a regular grid using 42 μm electrode spacing. The images and soma locations were then transformed into array coordinates, and spike locations were overlaid with the retinal image.

SUPPLEMENTAL INFORMATION

Supplemental Information includes Supplemental Experimental Procedures and one figure and can be found with this article online at http://dx.doi.org/10.1016/j.celrep.2017.02.038.

AUTHOR CONTRIBUTIONS


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