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Euclid: The selection of quiescent and star-forming galaxies using observed colours


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ABSTRACT

The Euclid mission will observe several billions of galaxies out to \(z \sim 6\) and beyond. This will offer an unrivalled opportunity to investigate several key questions for understanding galaxy formation and evolution. The first step for many of these studies will be the selection of a sample of quiescent and star-forming galaxies, as is often done in the literature by using well known colour techniques such as the ‘UVJ’ diagram. However, given the limited number of filters available for the Euclid telescope, the recovery of such rest-frame colours will be challenging. We therefore investigate the use of observed Euclid colours, on their own and together with ground-based \(u\)-band observations, for selecting quiescent and star-forming galaxies. The most efficient colour combination, among the ones tested in this work, consists of the \((u-VIS)\) and \((VIS-J)\) colours. This combination allows users to select a sample of quiescent galaxies complete to above \(\sim 70\%\) and with less than \(15\%\) contamination at redshifts in the range \(0.75 < z < 1\). For galaxies at high-z or without the \(u\)-band complementary observations, the \((VIS-Y)\) and \((J-H)\) colours represent a valid alternative, with \(> 65\%\) completeness level and contamination below 20% at \(1 < z < 2\) for finding quiescent galaxies. In comparison, the sample of quiescent galaxies selected with the traditional UVJ technique is only \(\sim 20\%\) complete at \(z < 3\), when recovering the rest-frame colours using mock Euclid observations. This shows that our new methodology is the most suitable one when only Euclid bands, along with \(u\)-band imaging, are available.

Key words: keyword1 – keyword2 – keyword3

1 INTRODUCTION

Galaxies show a clear bimodality in the distribution of their rest-frame ultraviolet and optical colours. Therefore, such
colours are often considered to distinguish and study different galaxy populations (Strateva et al. 2001; Blanton et al. 2003b; Baldry et al. 2004; Bell et al. 2004; Peng et al. 2010; Moresco et al. 2013; Jin et al. 2014; Fritz et al. 2014). Because the optical spectrum of galaxies is dominated by the integrated light of their stellar population, any relation between their colours and magnitudes reflects differences in their star-formation histories, dust content, and metallicities.

For these reasons, the rest-frame \( U - V \) colours have been extensively compared to the overall visible magnitude with the goal to separate between quiescent and star-forming galaxies - and thus galaxies with different star-formation histories - using a simple but effective method (Giallongo et al. 2005; Cassata et al. 2007; Labbé et al. 2007; Wyder et al. 2007; Jin et al. 2014; Lin et al. 2019). However, galaxy observations at higher redshifts, i.e., \( z \sim 3 \), required the addition of near-IR colours, such as the rest-frame \( J \) band, in order to distinguish between highly dusty, star-forming systems and quiescent galaxies (Pozzetti & Mannucci 2000; Wypts et al. 2007). As a consequence, the use of colour-colour diagrams such as the \( UVJ \) technique has become a standard way to characterise galaxy populations and to study how they evolve through time (e.g., Mendel et al. 2015; Fang et al. 2018).

The rest-frame \( (U - V) \) and \( (V - J) \) colours of galaxies have furthermore been demonstrated to evolve minimally with redshift (Williams et al. 2009; Whitaker et al. 2011). Although the rest-frame colours of galaxies are highly dependent on the spectral energy distribution (SED) modelling, overall, they can be considered sufficiently accurate for normal galaxies if multiple bands are available.

\begin{table}[h]
\centering
\caption{10\textsigma depth in AB magnitude, central wavelength and full width half maximum (FWHM) of the four \textit{Euclid} filters and the CFSI/\textit{u} bands. The Deep Survey will be two magnitudes deeper than the primary survey in all bands.}
\begin{tabular}{lccc}
\hline
\textbf{band} & \textbf{10\textsigma depth} & \textbf{central wavelength [\textmu m]} & \textbf{FWHM [\textmu m]} \\
\hline
\textit{V}IS & 24.50 & 7150 & 3640 \\
\text{NISP}/\textit{Y} & 23.24 & 10850 & 2660 \\
\text{NISP}/\textit{J} & 23.24 & 13750 & 4040 \\
\text{NISP}/\textit{H} & 23.24 & 17725 & 5020 \\
\text{CFSI}/\textit{u} & 24.20 & 3715 & 510 \\
\hline
\end{tabular}
\end{table}

\textit{Euclid}\(^1\) is a European Space Agency mission with the aim of mapping the geometry of the Universe and studying the evolution of cosmic structures and the distance-redshift relation. In order to achieve this goal, \textit{Euclid} will derive precise shapes and redshift measurement for several billions of galaxies out of \( z \sim 3 \) and it will observe several billions of galaxies out of \( z \sim 6 \). \textit{Euclid} has a 1.2 m primary mirror and two instruments on board. The visible (\textit{VIS}) instrument will provide high-quality visible imaging with an extremely wide broad-band filter covering between 550 and 900 nm and a mean image quality of \( \sim 0.7" 23 \) (Cropper et al. 2010). The complementary Near Infrared Spectrometer and Photometer (NISP) instrument will cover wavelengths from 900 to 2000 nm with three broad-band filters, i.e., \( Y, J, \) and \( H \) (see Figure 1), and a low-resolution slitless spectrometer (Schweitzer et al. 2010). The \textit{Euclid} Wide Survey is expected to cover 15,000 deg\(^2\) down to 10\textsigma depth of 24.5 magn in the visible filter and down to a 5\textsigma depth of 24.0 magn at near-infrared wavelengths. A deep survey two magnitudes deeper than the main survey will also be conducted over 40 deg\(^2\) in the \textit{Euclid} Deep Fields. In addition to these main \textit{Euclid} surveys, extensive plans are in place to complement \textit{Euclid} observations with ground-based data from the ultraviolet to visible light (Laureijs et al. 2010; Ibata et al. 2017) in order to improve the sampling quality of the SED for each galaxy. This is of course very challenging, given that the goal is to observe uniformly almost the entire extra-galactic sky with \textit{Euclid} depth, using ground-based instruments.

Overall, this extraordinary galaxy survey will be crucial not only for cosmological studies, but also to investigate several Legacy science key questions, especially related to galaxy formation and evolution. Given that quiescent and star-forming galaxies represent the two most common evolutionary phases of galaxies, and considering the large amount of galaxies that will be observed by \textit{Euclid}, it is essential to obtain a fast and reliable criterion to select quiescent and star-forming galaxies with the \textit{Euclid} photometric capability, as this will be the first step for many future studies. One of the dominant difficulties for this endeavour is the main \textit{Euclid} filter, \textit{VIS}: it is especially designed for \textit{Euclid} and has therefore never been used, and it boasts an uncommonly large wavelength range (see Table 1). It is important to fully characterise the use of this filter for galaxy evolution studies, and a central part of this is the ability to distinguish between star-forming and passive galaxies.

The aim of this work is to use a set of mock \textit{Euclid} observations to analyse the efficiency of different \textit{Euclid} observed colours for separating quiescent and star-forming galaxies. The structure of the paper is the following: in section 2 we describe the derivation of the mock observations following three different methods. In section 3 we report the quiescent galaxies selection and the use of the standard rest-frame \( U, V, \) and \( J \) colours to separate star-forming and quiescent galaxies. The capability of the different \textit{Euclid} observed colour combinations on isolating quiescent galaxies is then evaluated in section 4. We summarise our main finding in section 5.

Throughout this paper, we use a Chabrier initial mass function (Chabrier 2003), and a \( \Lambda \text{CDM} \) cosmology with \( H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1} \), \( \Omega_m = 0.27 \), \( \Omega_k = 0.73 \) and all magnitudes are in the AB system (Oke & Gunn 1983).

\section{Mock Observations}

We derive mock observations for the four broad-band filters on board \textit{Euclid} which are the visible \textit{VIS} filter and the NISP instrument’s \( Y, J, \) \( H \) filters. We also include the \( u \)-band from the Canada-France Imaging Survey (CFIS) in our analysis. This band, as well as other ground-based optical bands such as the similar \( u \)-band from the Large Synoptic Survey Telescope (LSST; Ivezic et al. 2008), will be available over a large fraction of the fields (around 2/3 of \textit{Euclid} sky for CFIS) in order to complement \textit{Euclid} observations (Ibata et al. 2017). The 5 filter throughputs we consider are shown in Figure 1 and the central wavelengths and widths

\footnote{\url{http://sci.esa.int/euclid/}}
are reported in Table 1. Our work focuses on the capability of the Euclid mission. While ancillary data will become available, it will not be homogeneous and may not cover the full area observed by Euclid. Nevertheless, we also include u-band data in our analysis, as these additional data will allow for maximal wavelength coverage. Additional improvements are expected if all 5 ancillary broad-bands (u, g, r, i, and z) are available.

We derive fluxes for real and simulated galaxies in these bands using three different approaches that are summarised in Table 2. Two of these methods are based on galaxies observed with current facilities and taken from the Cosmos Evolution Survey (COSMOS, Scoville et al. 2007), while the third one is based on the MICE Simulation and it is based on theoretical SEDs. In all cases we consider separately the observational depth expected for the Euclid Wide and Euclid Deep Surveys. However, the COSMOS2015 catalogue is similar or shallower than the Euclid Deep Survey, therefore many faint galaxies that will be detected with the Euclid Deep Survey are missing in this catalog.

2.1 Mock Euclid fluxes from real galaxies

We start our work from the public COSMOS2015 catalogue (Laigle et al. 2016) which contains multi-wavelength observations of more than a million objects over the 2 deg² of the COSMOS field. From the COSMOS2015 catalogue we consider 30 bands, from the GALEX (Zamojski et al. 2007) near-UV filter around 0.23 µm to the Spitzer/IRAC band at 4.5 µm (Sanders et al. 2007). We use aperture magnitudes within 3 arcsec and correct for photometric offsets, systematic offsets and galactic extinction, as suggested in Laigle et al. (2016). Briefly, the first offset is derived from photometric data to correct for the incompleteness in the flux measured inside the fixed aperture. The second one is obtained comparing the observed colours with the colours predicted with several theoretical templates, i.e. templates from Polletta et al. (2007) and Bruzual & Charlot (2003), for a sample of galaxies with spectroscopic redshifts. The galactic extinction includes the foreground extinction derived by Allen (1976). We remove from the sample objects that are flagged as having inadequate optical photometry (FLAGPETER> 0) and objects that are labelled as stars or X-ray sources in the COSMOS2015 catalogue. The 3673 X-ray sources in the catalogue are mainly active galactic nuclei and account for a small fraction compared to the final galaxy population. However, a similar selection should always be color-reconsidered before applying the criteria we offer in this paper to future Euclid samples. The final catalogue consists of 518 404 galaxies with photometric redshifts up to z∼6.

For all the galaxies in the catalogue, we derive mock fluxes and magnitudes for the VIS, Y, J, and H Euclid bands and the CFIS/u filter using two different approaches and considering the observational depth expected both for the Euclid Wide and Euclid Deep Surveys. However, the COSMOS2015 is significantly shallower than the Euclid Deep Survey, therefore many faint galaxies that will be detected with the Euclid Deep Survey are missing in this catalog.

2.1.1 The Int data set

The first method to derive Euclid mock observations is based on a linear interpolation among the 30 broad-band filters available in the COSMOS2015 catalogue. In particular, we use a broken line that connects the available COSMOS2015 observations as a proxy of each galaxy spectrum. We then interpolate this broken “spectrum” with the Euclid filter throughputs. For the J, Y and H filters this method is similar to interpolating the adjacent observed filters, but the described method is necessary to achieve a correct estimation of observations in the wide VIS band. We do not include additional scatter to mimic the expected Euclid photometric errors, because the observational depth of the COSMOS2015 catalogue is similar or shallower than the one expected for the Euclid Surveys. For example, the observed magnitude errors in the COSMOS2015 J (Y) band are on average 1.5 (3) times smaller than the magnitude errors expected for the Euclid J (Y) filter, assuming the observational depth of the Euclid Wide Survey. On the other hand, magnitude errors in the COSMOS2015 H band are similar to the expected

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**Table 2.** Summary of the different types of simulated data used in this work.

<table>
<thead>
<tr>
<th>Name</th>
<th>Origin</th>
<th>N_{objects}</th>
<th>N_{phantom}</th>
</tr>
</thead>
<tbody>
<tr>
<td>SED Wide</td>
<td>SED fitting from COSMOS2015</td>
<td>3249101</td>
<td>213837</td>
</tr>
<tr>
<td>SED Deep</td>
<td>SED fitting from COSMOS2015</td>
<td>5121526</td>
<td>307961</td>
</tr>
<tr>
<td>Int Wide</td>
<td>Interpolation from COSMOS2015</td>
<td>315755</td>
<td>21988</td>
</tr>
<tr>
<td>Int Deep</td>
<td>Interpolation from COSMOS2015</td>
<td>517890</td>
<td>30990</td>
</tr>
<tr>
<td>Mice Wide</td>
<td>MICE-Grand Challenge Galaxy v.2.0</td>
<td>12982</td>
<td>2576</td>
</tr>
<tr>
<td>Mice Deep</td>
<td>MICE-Grand Challenge Galaxy v.2.0</td>
<td>45162</td>
<td>3050</td>
</tr>
</tbody>
</table>

**Figure 1.** Throughput of the four main Euclid filters (solid black lines). From left to right, these are the VIS filter, NISP/Y, NISP/J, and NISP/H filters. We also include the throughput of the CFIS/u band filter (dashed black line). The red dots indicate the observed wavelength of the 4000Å-break at different redshifts.
Euclid H band errors for the Euclid Wide Survey. Hereafter we refer to mock observations derived by using this method, and based on the 518,404 galaxies selected from the COSMOS2015 catalogue, as data sets Int Wide and Int Deep, depending on the assumed observational depth. In summary, the two data sets have, respectively, 315,755 and 517,890 galaxies detected (S/N>3) in the VIS band considering the two different observational depths.

2.1.2 The SED data set

In the second approach, we derive the mock observations from the best theoretical template that describes the SED of each galaxy, using the 30 filter observations of the COSMOS2015 catalogue. In particular, we use the public code LePhare (Arnouts et al. 1999; Ilbert et al. 2006) and consider Bruzual & Charlot (2003) templates with solar and subsolar (0.008 Z⊙) metallicities, exponentially declining star formation histories with timescale τ between 0.1 and 10 Gyr, ages between 0.1 and 12 Gyr, Calzetti et al. (2000) reddening law and 12 values of colour excess between 0 and 1. We did not apply any cut in S/N on the observed COSMOS2015 observations and we considered magnitude errors and upper limits as derived by Laigle et al. (2016). We only apply a lower limit to the magnitude errors, i.e. 0.01 mag, in order to avoid the fit to be driven by single observations. We only consider exponentially declining star-formation histories, since, in general, they well describe the bulk of the quiescent galaxy population at z<3. We will see this again later in this work, when we report similar results of the SED data set and the data sets described in the previous paragraph (Int Wide and Deep), that have different assumption on star-formation histories.

We also allow the code to add nebular emission lines, as explained in Ilbert et al. (2006). Note that the effect of including nebular emission lines in the fit is minor, given that this work focus on galaxies at z<3 and nebular emission lines are more prominent in high-z galaxies (Fumagalli et al. 2012; Mármol-Queraltó et al. 2016). Moreover, equivalent widths higher than ∼ 350 Å, ∼ 200 Å, ∼ 390 Å and, ∼ 450 Å are necessary to produce a detectable boost (>0.1 mag) in the VIS, Y, J and, H filters, respectively. In addition, during the fit we fix the redshift to the value present in the COSMOS2015 catalogue and the age of each galaxy is constrained to be smaller than the age of the Universe at the galaxy redshift. After deriving the best SED templates we randomise each flux 10 times using a normal distribution centred on the flux value and with a standard deviation equal to the expected flux error, which depends on the assumed survey depth and is defined as one tenth of the flux corresponding to a S/N=10. We remind the reader that a S/N = 10 corresponds to 24.50 (26.50) AB mag in the VIS band (see Table 1 for the depth in each filter) for the Wide (Deep) Survey. Hereafter we refer to mock observations derived using this method as data set SED Wide or SED Deep, depending on the assumed observational depth. The data set SED Wide consists of 3249 101 mock galaxies with detection in the VIS band, while the SED Deep catalogue contains 5 121 526 mock galaxies.

We also infer rest-frame U, V, and J colours and the specific star formation rate (sSFR) of each galaxy from the best SED template. Rest-frame U, V, and J colours have been derived considering the band-pass from Maíz Apellániz (2006) for the U and V band and the Two Micron All Sky Survey (Skrutskie et al. 2006) J band. The U, V, and J rest-frame colours derived in this work are consistent with those in the COSMOS2015 catalogue. We re-calculate these rest-frame colours for consistency, as later in the paper we also present the same rest-frame colours derived using the Euclid mock observations. For the rest of the paper we consider the sSFR derived in this way as the true sSFR associated with each galaxy in the SED and Int data sets. Moreover, in the rest of the paper, we assign to each galaxy its true redshift, which corresponds to the redshift from either the SED template or real observation from which we derive the Euclid mock observations. However, we assume it will be possible to recover photometric redshifts with an accuracy good enough for the redshift bins considered here, i.e., σz =0.25 or 0.5 at z>1.5. This is more than realistic given that the requirement to perform Euclid cosmological studies is to have a photometric redshift accuracy of σz < 0.05 (1 + z).

The two methods described in this section are complementary. The first one depends on the observed COSMOS2015 photometric errors, which may not completely match the future Euclid photometric uncertainties but it has few model assumptions (i.e., the photometric offsets are derived from theoretical templates), while the second one depends on the theoretical templates, reddening law and, star formation histories used for the SED fit, but matches the expected Euclid photometric errors. The data sets differ in the numbers of galaxies because of the adopted Survey depth and the different approaches used to include photometric errors. We remind the reader that we randomise 10 times the observed galaxies in the SED data sets to mimic the expected Euclid photometric errors. On the other hand, we did not randomise the fluxes in the Int data sets because the COSMOS2015 photometric errors already influence the broken “spectrum” used to derive the mock observations.

2.2 Mock Euclid fluxes from simulations

We complete our data sets with mock observations obtained from the Euclid internal Scientific Challenge (SC456) that use galaxy properties based on the MICE-Grand Challenge Galaxy v.2.0 simulation2 (Carretero et al. 2015; Fosalba et al. 2015b,a; Crocce et al. 2015). This simulation is designed to mimic the observational depth and conditions of the actual Euclid survey. It is therefore a theoretical determination which complements our observational inference of colours described in the previous subsection. Adding simulated galaxies with known input parameters to our analysis offers the advantage of providing full control over measurement errors while minimising systematic errors. The simulation catalogue was generated using a hybrid Halo Occupation Distribution and Halo Abundance Matching prescriptions to populate Friends of Friends dark matter halos and using the following cosmological parameters: Ωm = 0.25, σ8 = 0.8, nS = 0.95, hΩb = 0.044, ΩΛ = 0.75, and h = 0.7. These values of Ωm and ΩΛ are slightly different from those used in the creation of the other mock observations, but the

2 http://www.ice.csic.es/en/content/68/mice-simulations
impact is negligible on our results as they do not influence galaxy colours.

The catalogue was built to follow a number of local observational constraints, among which are i) the luminosity function at $z = 0.1$ (Blanton et al. 2003a), ii) the galaxy clustering as a function of luminosity and colour as observed in the Sloan Digital Sky Survey up to $z = 0.25$ (Zehavi et al. 2011) and iii) the colour-magnitude diagram of galaxies at $z < 0.3$ (Blanton et al. 2005). A template taken from the SED library of Ilbert et al. (2009) is associated to each galaxy in the simulation. This library includes templates from Bruzual & Charlot (2003), with ages ranging from 3 to 0.03 Gyr, and template for elliptical and spirals galaxies from Polletta et al. (2007). The final catalogue is complete down to an intrinsic magnitude $M_\star < -18.9$, which corresponds to galaxies with apparent magnitudes $H \sim 23$ at $z = 1.4$. Further details on the galaxy catalogue can be found in Crocce et al. (2015).

We include photometric errors by randomising each flux 10 times by considering a normal distribution centred on the real value and with a standard deviation equal to the noise expected for the Euclid Wide Survey and the Euclid Deep Survey, respectively (see Table 1). The Mice simulation has a restricted number of quiescent galaxies with detection in the $u$ band, therefore this data set is not used to derive colour selections including this band. Hereafter we refer to mock observations derived by using this method as data set Mice Wide and Mice Deep, depending on the assumed observational depth. Both data sets are created from a sample of 80 790 mock galaxies limited to $z<2.3$. Because of the completeness of the MICE catalogue, the mock catalogue Mice Deep created in this work is missing part of the population of faint galaxies expected in the Euclid Deep Survey.

A general comparison of the properties of the Mice, Int, and SED Wide data sets is presented in Appendix A.

3 QUIESCENT GALAXIES INITIAL SELECTION

In this section we first describe the initial selection of quiescent galaxies and then we investigate the accuracy of the selection of quiescent galaxies with the use of $U$, $V$, and $J$ rest-frame colours as well as the sSFR, all derived from the Euclid filters.

In the literature, several studies have identified quiescent galaxies using a fixed threshold in sSFR. However, this threshold is not uniform and varies depending on the properties of the data set (McGee et al. 2011; Wetzel et al. 2012; Lin et al. 2014). This is motivated by the minimum visible in the bimodal distribution of the sSFR of galaxies at low redshift (Kauffmann et al. 2003; Wetzel et al. 2013; Renzini & Peng 2015; Bisigello et al. 2018). In the following, we define star-forming galaxies as objects with

$$\log_{10}(\text{sSFR/yr}^{-1}) > -10.5,$$

while quiescent galaxies have

$$\log_{10}(\text{sSFR/yr}^{-1}) < -10.5.$$

For the initial selection in the data sets SED and Int, we obtain the sSFR of each galaxy from the SED template that best describes the 30 bands of the COSMOS2015 catalogue.

Mock observations derived with the Mice simulation (data sets Mice) do not include a sufficient number of galaxies with detection in the CFIS/$u$-band filter and, therefore, for these data sets we limit our analysis to colours including the VIS and NISP filters. The sSFR for these data sets is taken from the Mice simulation catalogue.

Throughout the paper we will test the different selection criteria by comparing them with the above-mentioned selection of quiescent galaxies done using the observations in the 30 COSMOS2015 bands or the Mice simulation. The number of quiescent galaxies in each data set is reported in Table 2. We evaluate the different methods to derive quiescent galaxies considering three different quantities.

(i) The mixing of quiescent and star-forming galaxies. This is defined as the percentage of galaxies inside the intersection between the areas containing 68% of both populations, looking at their number density distributions in colour space.

(ii) The completeness (C). This consists of the fraction of quiescent (or star-forming) galaxies that is correctly recognised by the analysed selection criteria.

(iii) The false-positive fraction (FP). This is the fraction of star-forming galaxies that is wrongly identified as quiescent by the analysed selection criteria, or vice-versa, the fraction of quiescent galaxies that is erroneously identify as
To derive the rest-frame colours with \textit{Euclid} we now investigate if it is possible to recover the correct rest-rate galaxy types in the original COSMOS2015 catalogue.

3.1 Deriving \textit{UVJ} majority of quiescent galaxies selected with the specified cut and star-forming galaxies. This test confirms that the they are close to our separation boundary between quiescent and star-forming galaxies (see section 3). The completeness (C) and false-positive fraction (FP) for the selection of quiescent galaxies is shown at the top left with the corresponding Poisson errors.

As a first test, we compare the rest-frame colours \((U - V)\) and \((V - J)\) with the sSFR, both from the COSMOS2015 catalogue. This is done to verify the goodness of our initial selection of quiescent galaxies. We report this comparison in Figure 2. As the \((U - V)\) and \((V - J)\) colour selection was derived from the empirical galaxy SED, we expect the two methods to show large consistency. Indeed, star-forming and quiescent galaxies show little mixing in the \textit{UVJ} plane and they are well separated by the criteria described in Whitaker et al. (2011) for different redshifts - black solid (for \(z = 0\)) and dotted (for \(z = 3\)) lines. Overall, the sSFR and \textit{UVJ} selections agree in 97% of quiescent galaxies, but there are 34% misclassified star-forming galaxies. However, these are galaxies with average \(\log_{10}(sSFR/\text{yr}^{-1}) \sim -10.2\). This implies that these are not extreme star-forming systems but they are close to our separation boundary between quiescent and star-forming galaxies. This test confirms that the majority of quiescent galaxies selected with the specified cut in sSFR is consistent with a selection using \textit{UVJ} colours.

Given the success of the \textit{UVJ} colour combination to separate galaxy types in the original COSMOS2015 catalogue, we now investigate if it is possible to recover the correct rest-frame \((U - V)\) and \((V - J)\) colours from \textit{Euclid} observations. To derive the rest-frame colours with \textit{Euclid} observations, we apply the same method that we also used with 30 COSMOS2015 bands (see subsection 2.1): the algorithm searches for the theoretical SED template that best describes the four \textit{Euclid} mock observations. However, we let the redshift vary in the fit, similar to future analysis with \textit{Euclid} observations.

Figure 3 shows results for the \textit{SED Wide} data set. In the figure we compare the selection done in the \textit{UVJ} plane using the 30 COSMOS2015 bands to the selection done in the same plane using the four \textit{Euclid} filters \(VIS, Y, J, H\). The majority of star-forming galaxies are properly recognised even using only the four \textit{Euclid} filters, as is evident from the high completeness (87%) of the recovered star-forming population, and the relatively low false-positive fraction (10%) of the quiescent galaxy population. However, a very large fraction, around 80%, of quiescent galaxies are wrongly identified as star-forming galaxies. The results do not change much if we limit our analysis to \(z<1\), as the completeness and false-positive fraction for quiescent galaxies are still 20% and 10%, respectively.

To identify the reason of the low fraction of quiescent galaxies recovered, we repeat the SED fit twice. First we fix the redshift to the “true” one, then we include the photometric redshift precision expected for \textit{Euclid}, i.e. \(\sigma_z < 0.05(1 + z)\). In the first case, both the completeness and false positive fraction for quiescent galaxies increase, but only to 41% and 31%, respectively. Results are similar considering the photometric redshift precision of \textit{Euclid}, i.e., \(C_{\text{quiescent}} = 40\%\) and \(FP_{\text{quiescent}} = 32\%\). This highlights the challenge of recovering the right SED template - and therefore the correct \((U - V)\) and \((V - J)\) rest-frame colours with only four \textit{Euclid} bands. This is valid even with high precision redshifts.

We also test whether we can use the sSFR, recovered from observations of the four \textit{Euclid} filters alone, to sepa-
ies that are part of the SED Wide sSFR distribution for quiescent and star-forming galaxies to retrieve the sSFR. In Figure 4, we show the recovered same SED template from which we derived the rest-frame rate between star-forming and quiescent galaxies. We use the Euclid observations in the Euclid Wide (green solid lines) and Deep Survey (orange dashed lines) as well as for the subsample of galaxies with both u and VIS band observations in the Euclid Wide (black solid lines) and Deep Survey (blue dashed lines). Results are shown for mock observations in the SED Wide and Deep data sets.

Figure 5. Redshift (right), stellar mass (center) and sSFR (left) number density distribution of galaxies. We show the distributions for the sample of galaxies with VIS observations in the Euclid Wide (green solid lines) and Deep Survey (orange dashed lines) as well as for the subsample of galaxies with both u and VIS band observations in the Euclid Wide (black solid lines) and Deep Survey (blue dashed lines). Results are shown for mock observations in the SED Wide and Deep data sets.

investigated in future work. To resemble the UVJ plane, we first include the ground-based CFIS/u band that will be available to complement Euclid observation over much of the fields. Similar u-band filters will be available through LSST and other ground-based imaging surveys.

In Figure 5 we show the redshift, stellar mass and sSFR distributions of galaxies with VIS observations (Wide and Deep) and the subsamples with both u-band and VIS detections (Wide and Deep), considering the different observational depths expected for both filters in the two Surveys (see Table 1). Overall, around 63% (96%) of galaxies in the Euclid Wide (Deep) Survey with VIS observations are detected in the u-band as well. Not surprisingly, the u-band observations limit the sample to low-redshift galaxies, however for the Euclid Wide Survey they also exclude from the sample some of the less massive galaxies. In the future, it will be necessary to take into account this sample selection when considering colour criteria including the u-band filter.

Figure 6 shows the colours derived from the best SED template (data set SED Wide) obtained by including photometric errors, as explained in subsection 2.1. We found similar results for the other data sets, i.e., SED Deep, Int Deep and Int Wide (section 2), as listed in Table 3. Results are shown for mock galaxies up to z=3. For each observed colour combination, we derive the percentage of quiescent and star-forming galaxies overlapping in colour-space, as this is an indication of the effectiveness of the method. This is done by comparing the number density distribution of the quiescent and star-forming galaxy populations in each colour-space and then deriving the percentage of galaxies inside the intersection between the areas containing 68% of both populations.

The separation between the quiescent and star-forming galaxies is relatively efficient when considering the (u−VIS) and (VIS−J) observed colours (Figure 6, last panel), as quiescent and star-forming galaxies overlap only outside the 68% areas in these colours. On the other hand, when we consider Euclid filters alone, i.e., without the additional information from the u-band, a large fraction (more than 20%) of quiescent and star-forming galaxies overlap in colour-space in the 68% areas. Overall, among all the colour combinations that include only Euclid filters and considering the average among all data sets (see Table 3), the (VIS−Y) vs. (J−H) is the one with the smallest overlap between the two galaxy populations, even if only by a few percentage units. The real potential of this colour combination is revealed when analysing the overlap at different redshifts, as it will become obvious from the analysis in the next sections.

In the next section, we further investigate the possibility of isolating quiescent galaxies at different redshift intervals using the observed colours that will be available through the Euclid Mission, i.e., the (u−VIS) vs. (VIS−J) and the (VIS−Y) vs. (J−H) colours. In addition, we also derive the best separation criteria for quiescent galaxies using the same Euclid colours.

4 COMPARISON OF Euclid COLOUR COMBINATIONS

We now investigate the ability to isolate quiescent galaxies from the star-forming galaxy population with various colour combinations available through Euclid observations. For this we use Euclid mock observations derived with the three methods described in the previous sections. We limit our analysis to the use of aperture photometry, but the inclusion of morphological and spectroscopic information is expected to improve the pureness of the sample (Moresco et al. 2013; Andreon 2018). The addition of these features will be
### Table 3.
Fraction of star-forming and quiescent galaxies occupying the intersection between the areas containing 68% of the two populations in different colour space at z < 3.

<table>
<thead>
<tr>
<th>Color</th>
<th>Population</th>
<th>SED Wide</th>
<th>SED Deep</th>
<th>Int Wide</th>
<th>Int Deep</th>
<th>Mice Wide</th>
<th>Mice Deep</th>
<th>Average</th>
</tr>
</thead>
<tbody>
<tr>
<td>(VIS - Y) vs. (Y-H)</td>
<td>quiescent</td>
<td>31%</td>
<td>36%</td>
<td>37%</td>
<td>44%</td>
<td>56%</td>
<td>44%</td>
<td>48.3%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>23%</td>
<td>35%</td>
<td>33%</td>
<td>51%</td>
<td>23%</td>
<td>23%</td>
<td>31.3%</td>
</tr>
<tr>
<td>(VIS - Y) vs. (Y-J)</td>
<td>quiescent</td>
<td>39%</td>
<td>46%</td>
<td>38%</td>
<td>46%</td>
<td>60%</td>
<td>52%</td>
<td>45.8%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>29%</td>
<td>42%</td>
<td>37%</td>
<td>52%</td>
<td>34%</td>
<td>23%</td>
<td>36.2%</td>
</tr>
<tr>
<td>(VIS - J) vs. (J-H)</td>
<td>quiescent</td>
<td>28%</td>
<td>32%</td>
<td>42%</td>
<td>45%</td>
<td>56%</td>
<td>51%</td>
<td>42.3%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>32%</td>
<td>36%</td>
<td>33%</td>
<td>52%</td>
<td>27%</td>
<td>22%</td>
<td>31.7%</td>
</tr>
<tr>
<td>(VIS - H) vs. (Y-J)</td>
<td>quiescent</td>
<td>45%</td>
<td>41%</td>
<td>41%</td>
<td>48%</td>
<td>55%</td>
<td>52%</td>
<td>47.0%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>32%</td>
<td>43%</td>
<td>37%</td>
<td>53%</td>
<td>34%</td>
<td>23%</td>
<td>37.0%</td>
</tr>
<tr>
<td>(u - VIS) vs. (VIS-J)</td>
<td>quiescent</td>
<td>30%</td>
<td>31%</td>
<td>25%</td>
<td>44%</td>
<td>55%</td>
<td>47%</td>
<td>38.7%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>19%</td>
<td>30%</td>
<td>30%</td>
<td>50%</td>
<td>32%</td>
<td>26%</td>
<td>31.2%</td>
</tr>
<tr>
<td>(VIS - Y) vs. (J-H)</td>
<td>quiescent</td>
<td>45%</td>
<td>41%</td>
<td>41%</td>
<td>48%</td>
<td>55%</td>
<td>52%</td>
<td>47.0%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>32%</td>
<td>43%</td>
<td>37%</td>
<td>53%</td>
<td>34%</td>
<td>23%</td>
<td>37.0%</td>
</tr>
<tr>
<td>(VIS - Y) vs. (Y-H)</td>
<td>quiescent</td>
<td>30%</td>
<td>31%</td>
<td>25%</td>
<td>44%</td>
<td>55%</td>
<td>47%</td>
<td>38.7%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>19%</td>
<td>30%</td>
<td>30%</td>
<td>50%</td>
<td>32%</td>
<td>26%</td>
<td>31.2%</td>
</tr>
<tr>
<td>(u - VIS) vs. (VIS-J)</td>
<td>quiescent</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>15%</td>
<td>0%</td>
<td>0%</td>
<td>2.5%</td>
</tr>
<tr>
<td></td>
<td>star-forming</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>40%</td>
<td>0%</td>
<td>0%</td>
<td>6.7%</td>
</tr>
</tbody>
</table>

**Figure 6.** *Euclid* observed colours for mock galaxies in the data set *SED Wide* at z < 3. The panels show different combinations of *Euclid* observed colours. Galaxies are colour-coded depending on their original sSFR value (see text). The blue and red lines show the 99.7% (solid lines), 95% (dashed lines) and 68% (dotted lines) contours of the number density of star-forming [log(sSFR/yr⁻¹)] > −10.5 and quiescent galaxies [log(sSFR/yr⁻¹)] < −10.5, respectively. At the top left of each panel we report the fraction of quiescent and star-forming galaxies occupying the intersection between the areas containing 68% of the two populations.
Figure 7. The \((u - VIPS)\) vs. \((VIPS - J)\) colours obtained from the data set SED Deep. Data are shown at different redshifts, from 0 (top left) to 1.5 (bottom right). Galaxies are colour coded depending on their original sSFR. The blue and red lines show the 99.7% (solid lines), 95% (dashed lines) and 68% (dotted lines) contours of the number density of star-forming \(\log_{10}(sSFR/\text{yr}^{-1}) > -10.5\) and quiescent galaxies \(\log_{10}(sSFR/\text{yr}^{-1}) < -10.5\), respectively. At the top left of each panel we report the completeness (C) and false-positive fraction (FP) of the quiescent galaxy selection with the corresponding Poisson errors. The black lines show the separation between quiescent and star-forming galaxies that maximises the quantity C (1 - FP).

Galaxies are not detected in the \(u\)-band in any substantial abundance. Therefore, other techniques will need to be used at higher redshifts. In addition, we remind the reader that, even at lower redshifts, the sub-sample of galaxies visible in the \(u\)-band in the Euclid Wide Survey is biased to higher stellar mass galaxies, as explained in section 4. The sample of quiescent galaxies detected in the \(u\)-band is substantially limited in the Mice simulation, so we consider only colours derived from real galaxy observations. In particular, we show colours that are determined from the best SED templates, however we note that colours obtained interpolating the original COSMOS2015 fluxes show a similar behaviour, and the analysis using these provide compatible results (see Table 4). The results for the Mice data sets, which we report only for completeness and we do not use further in the analysis, are consistent with the ones derived by using the SED data sets. To simulate photometric errors, we randomly scatter the fluxes of all bands, with a scatter that depends on the expected survey noise (see subsection 2.1). Thus we are mimicking as well as can be done the type of data that will be retrieved from Euclid observations.

Quiescent and star-forming galaxies show some evolution with redshift in both \((u - VIPS)\) and \((VIPS - J)\) colours. This is expected, since the filters trace different parts of the galaxy spectra at different redshifts, and also the best fitting galaxy templates evolve with redshift. Similarly to the \(UVJ\) colour selection, we describe the area occupied by quiescent galaxies at each redshift (black solid lines) as:

\[
(u - VIPS) > m(VIPS - J) + q, \quad (u - VIPS) > C_{\text{low}}, \quad \text{and} \quad (VIPS - J) < C_{\text{up}}.
\]

(1)

Considering this description, we derive the best line to isolate quiescent galaxies by maximising the quantity C (1 - FP). C is the completeness, i.e., the fraction of true quiescent galaxies not detected in the \(u\)-band in any substantial abundance.
Table 4. Best selection criteria for the \((u - VIS)\) and \((VIS - J)\) observed colours at different redshifts, as described in Equation 1. The last two columns report the completeness (C) and false-positive fraction (FP) of each selection.

<table>
<thead>
<tr>
<th>data set</th>
<th>(z)</th>
<th>(m_\text{up})</th>
<th>(q)</th>
<th>(C_{\text{low}})</th>
<th>(C_{\text{up}})</th>
<th>C</th>
<th>FT</th>
</tr>
</thead>
<tbody>
<tr>
<td>SED</td>
<td>0.125</td>
<td>1.4</td>
<td>1.1</td>
<td>2.0</td>
<td>2.4</td>
<td>74±1%</td>
<td>15±1%</td>
</tr>
<tr>
<td></td>
<td>0.375</td>
<td>0.9</td>
<td>1.8</td>
<td>2.6</td>
<td>1.7</td>
<td>92±1%</td>
<td>3±1%</td>
</tr>
<tr>
<td>Wide</td>
<td>0.625</td>
<td>1.7</td>
<td>0.0</td>
<td>2.8</td>
<td>2.0</td>
<td>84±1%</td>
<td>3±1%</td>
</tr>
<tr>
<td></td>
<td>0.875</td>
<td>0.7</td>
<td>1.2</td>
<td>2.1</td>
<td>2.4</td>
<td>79±1%</td>
<td>5±1%</td>
</tr>
<tr>
<td>SED</td>
<td>0.125</td>
<td>1.5</td>
<td>1.2</td>
<td>1.7</td>
<td>1.6</td>
<td>80±1%</td>
<td>14±1%</td>
</tr>
<tr>
<td></td>
<td>0.375</td>
<td>0.8</td>
<td>1.9</td>
<td>2.2</td>
<td>1.8</td>
<td>84±1%</td>
<td>4±1%</td>
</tr>
<tr>
<td>Deep</td>
<td>0.625</td>
<td>0.8</td>
<td>1.6</td>
<td>2.5</td>
<td>2.1</td>
<td>84±1%</td>
<td>3±1%</td>
</tr>
<tr>
<td></td>
<td>0.875</td>
<td>0.9</td>
<td>0.9</td>
<td>2.0</td>
<td>2.5</td>
<td>84±1%</td>
<td>1±1%</td>
</tr>
<tr>
<td>Mice</td>
<td>0.125</td>
<td>1.3</td>
<td>1.9</td>
<td>2.6</td>
<td>1.5</td>
<td>91±3%</td>
<td>11±1%</td>
</tr>
<tr>
<td></td>
<td>0.375</td>
<td>1.9</td>
<td>0.9</td>
<td>2.6</td>
<td>1.5</td>
<td>91±3%</td>
<td>11±1%</td>
</tr>
<tr>
<td>Int</td>
<td>0.125</td>
<td>1.1</td>
<td>1.7</td>
<td>1.3</td>
<td>1.8</td>
<td>83±4%</td>
<td>12±1%</td>
</tr>
<tr>
<td></td>
<td>0.375</td>
<td>0.8</td>
<td>1.5</td>
<td>0.0</td>
<td>2.2</td>
<td>72±5%</td>
<td>18±2%</td>
</tr>
<tr>
<td>Deep</td>
<td>0.625</td>
<td>1.7</td>
<td>0.6</td>
<td>2.7</td>
<td>1.8</td>
<td>54±1%</td>
<td>12±1%</td>
</tr>
<tr>
<td></td>
<td>0.875</td>
<td>0.5</td>
<td>1.9</td>
<td>2.5</td>
<td>2.9</td>
<td>61±1%</td>
<td>15±1%</td>
</tr>
<tr>
<td>Mice</td>
<td>0.125</td>
<td>1.3</td>
<td>1.0</td>
<td>2.0</td>
<td>1.6</td>
<td>95±9%</td>
<td>0±1%</td>
</tr>
<tr>
<td></td>
<td>0.375</td>
<td>0.9</td>
<td>1.5</td>
<td>2.8</td>
<td>1.6</td>
<td>94±17%</td>
<td>2±2%</td>
</tr>
<tr>
<td>Int</td>
<td>0.625</td>
<td>0.5</td>
<td>1.9</td>
<td>0.0</td>
<td>1.9</td>
<td>60±20%</td>
<td>16±9%</td>
</tr>
<tr>
<td>Deep</td>
<td>0.125</td>
<td>1.4</td>
<td>0.9</td>
<td>2.1</td>
<td>1.6</td>
<td>97±3%</td>
<td>12±1%</td>
</tr>
<tr>
<td>Mice</td>
<td>0.125</td>
<td>1.8</td>
<td>0.4</td>
<td>2.7</td>
<td>1.9</td>
<td>87±7%</td>
<td>3±1%</td>
</tr>
<tr>
<td></td>
<td>0.625</td>
<td>0.0</td>
<td>2.9</td>
<td>0.0</td>
<td>2.2</td>
<td>77±6%</td>
<td>15±2%</td>
</tr>
<tr>
<td>Deep</td>
<td>0.875</td>
<td>0.1</td>
<td>2.3</td>
<td>0.0</td>
<td>2.4</td>
<td>62±8%</td>
<td>19±4%</td>
</tr>
</tbody>
</table>

“*This data set is not used to derive the final colour selection as it is not big enough for statistical purposes.

Figure 8. Redshift evolution of the parameters in Equation 1 that describes the area isolating quiescent galaxies. From top to bottom: the slope, the intercept, the lower limit in \((u - VIS)\) colours and the upper limits in the \((VIS - J)\) colours. Mock observations are obtained from the best SED template describing the COSMOS2015 observations \((\text{orange squares})\) and from the interpolation of the COSMOS2015 observations \((\text{green triangles})\). We consider the observational depth planned for both the Euclid Wide Survey \((\text{filled symbols})\) and the Euclid Deep Survey \((\text{empty symbols})\). Black crosses correspond to the best-line derived considering the average completeness and false-positive fraction for the four data sets. Data points are slightly shifted horizontally for clarity. The red solid line shows the best fit for each parameter \((\text{see Equation 2})\), as derived from the average completeness and false-positive fraction.

We repeat the procedure for the data sets obtained from real galaxy observations \((\text{data sets SED and Int})\). All values derived for each data set are presented in Table 4. We then combine the results by averaging the completeness and false-positive fraction of all data sets in the considered parameter space and we derive the best separation line for quiescent galaxies by maximising again the quantity \(C(1 - \text{FP})\). It is necessary to highlight that we do not average the best lines of each data set, but we average the completeness and false positive fraction of each possible line in the 4 data sets and then derive the best line. Moreover, we did not apply any weight on the different data sets, as each of them has different drawbacks and strong points. For example, the \(\text{SED}\) data sets have photometric errors similar to what is expected for \(\text{Euclid}\), but the \(\text{Int}\) data do not a-priori assume a shape of the SED.

In order to have selection criteria available at different redshifts, we derive the redshift evolution of each parameter in Equation 1. This is done from the average completeness and false-positive fraction to ensure the stability of the final results compared to the method used to obtain mock observations. Because the errors of the parameters are correlated, we cannot perform an independent fit to the evolution of the parameters that describe the selection area. To bypass this issue, we therefore derive the evolution of each parameter in a sequential order. In particular, we start by extracting the redshift evolution of the \(m\) by considering the slope value that maximises the average completeness and minimises the average false-positive fraction. In the fit we include the marginalised errors obtained by selecting all slopes that result to \(C(1 - \text{FP}) > 0.975 \times C(1 - \text{FP})\). This corresponds to a maximum error of 10% of the \(C(1 - \text{FP})\) of any single data set. Second, we derive the redshift evolution of the intercept \(q\), considering all lines that satisfy the same \(C(1 - \text{FP})\) selection, but in addition have slope values equal to the ones predicted with the slope-redshift evolution. Similarly, we include the derived slope and intercept in the redshift evolution in the fit for the \(C_{\text{low}}\) redshift evolution and we include in this the evolution of both the slope \((m)\), the intercept \((q)\), and the \((u - VIS)\) lower limit \((C_{\text{low}})\) to derive the redshift evolution of the \((VIS - J)\) upper limit \((C_{\text{up}})\). The resulting redshift evolution of each parameter is
shown in Figure 8 and is described by:

\[ m = 0.91z^2 - 1.80z + 1.70, \]
\[ q = -3.40z^2 + 3.44z + 0.82, \]
\[ C_{\text{low}} = -2.17z^2 + 3.56z + 1.29, \]
\[ C_{\text{up}} = 1.18z + 1.70. \]

The evolution of the (\(VIS - J\)) limit (\(C_{\text{up}}\)) is well described by a linear relation, while we consider a quadratic polynomial for the slope \(m\), the intercept \(q\), and the (\(u - VIS\)) limit (\(C_{\text{low}}\)). The completeness and the false-positive fraction do not improve much if we consider higher-order polynomials, while the false-positive fraction increases if we consider lower-order polynomials for the slope \(m\) and the (\(u - VIS\)) limit.

We crosscheck the overall goodness of the derived selection criteria for isolating quiescent galaxies by calculating for our selection the completeness and false-positive fraction in the four data sets derived from real observations (Figure 9). The average fraction of false-positive is below 15\% at \(z \lesssim 1.25\), with a peak \(\sim 20\%\) at the highest redshift considered. At the same time, the average completeness is above 55\% at all redshifts, and the selection is particularly effective at 0.25 < \(z \leq 1\), where it is above \(\sim 70\%\). However, the completeness of the Int Deep data set is quite low. This is due to some galaxies with intermediate colours that are particularly faint and have large photometric errors in the Euclid Deep Survey and are too faint to be detected in the Euclid Wide Survey. The false-positive fractions is instead generally higher for the Int Wide data set. It is important to consider that both these data sets are affected by the photometric errors given by the COSMOS2015 catalogues that are generally larger than the errors expected for Euclid.

In Figure 9 we also show how the completeness and false-positive fraction vary with the observed \(VIS\) magnitude for galaxies at \(z \leq 1.5\). The average false-positive fraction remains almost constant (between 11\% and 16\%) around \(VIS\) between 18 and 25 mag, with lower values for brighter and fainter objects. On the other hand, a clear trend is visible between the completeness and the \(VIS\) observed magnitude, with an average completeness above 80\% at magnitudes brighter than 22 mag and a steady drop at fainter magnitudes. For both Deep Surveys the drop in completeness happens at around 23 mag for both the Int and SED data set. The difference between the completeness in the Wide and Deep Surveys are due to the different uncertainties associated to each galaxy but also to the different depths in the \(u\)-band, i.e. the Deep Survey is 2 magnitude deeper. At \(VIS \geq 22\) mag only the bluest quiescent galaxies are detected in the \(u\)-band. This selection is more important in the Wide Surveys than in the Deep ones (see also Figure 5). These are galaxies with relatively higher sSFR and are generally more difficult to disentangle from star-forming galaxies. To give a more quantitative example, galaxies in the \(SED\) Wide data set at \(z \lesssim 1.5\) and detected in the \(H\), \(J\), and \(u\) filters have a median log(10(sSFR/yr\(^{-1}\))) = \(-12.2\). The subsample of galaxies that have the same redshift and detection selection and also \(VIS > 22\) mag have median log(10(sSFR/yr\(^{-1}\))) = \(-11.1\). On the other hand, the same selections in the \(SED\) Deep data set produce less difference between the two subsamples that have median log(10(sSFR/yr\(^{-1}\))) = \(-11.8\) and \(-11.7\), respectively.

We conclude that the (\(u - VIS\)) vs. (\(VIS - J\)) colours can be used to isolate quiescent galaxies using the selection described in Equation 2 with a generally low contamination by star-forming galaxies and a completeness above 60\% at least up to \(z \sim 1\). For comparison, the \(UVJ\) diagram has been tested and used up to \(z \sim 3.5\), but, as we previously mentioned, the \(U\), \(V\), and \(J\) rest-frame colour are challenging to derive with only the four Euclid filters. Indeed, the quiescent galaxy population recovered at \(z < 1\) with the \(UVJ\) diagram with Euclid has a very low completeness (20\%, subsection 3.1), making the (\(u - VIS\)) and (\(VIS - J\)) observed colours preferable. This type of analysis will be important and critical when examining the large 15 000 deg\(^2\) Euclid survey area where automation and simplicity will be critical.

### 4.0.2 Redshift separation: the (\(VIS - Y\)) vs. (\(J - H\)) colours

We now investigate if a separation is possible using only the four bands available to Euclid. We therefore use the (\(VIS - Y\)) and (\(J - H\)) colours only, without the addition of any ground-based ancillary data. We do not analyse the redshift evolution of other Euclid colour combinations, as they overall show more mixing between star-forming and quiescent galaxies than the (\(VIS - Y\)) vs. (\(J - H\)) colours (Figure 6, Table 3). An idealised case of galaxies in the nearby Universe is shown in Figure 10 in which we plot Euclid observed colours (\(VIS - Y\)) vs. (\(J - H\)) from the Mice simulation in the lowest redshift bin, with no addition of photometric errors. Different galaxy populations are indicated by circles and show idealised trends of an evolving galaxy in this colour-colour space. Star-forming galaxies are expected to have blue (\(VIS - Y\)) and (\(J - H\)) colours, before steadily moving to redder colours as they decrease their star-formation activity and the amount of dust in these systems increases, with a clear separation between quiescent galaxies and dusty star-forming systems.

Moving away from this idealised case, the inclusion of photometric errors as well as redshift evolution makes the selection of quiescent galaxies more challenging, as shown in Figure 11. We show the selection up to \(z = 3\) only, because only a few quiescent galaxies are present in our data sets at higher redshifts, which naturally leads to poor separations. Colours are shown for the data set SED Wide and they are overall similar to the colours of the other five data sets.

We overall find that the star-forming and quiescent galaxies show similar (\(VIS - Y\)) and (\(J - H\)) colours at low redshift and their separation becomes clearer and cleaner with increasing redshift. This is mainly due to the absence of filters tracing the \(\lambda = 4000\) Å-break at \(z < 1\), which is the most prominent feature of an old stellar population. This is not surprising given that the science goals of the Euclid mission focus their attention at \(z > 1\). At \(z > 1\), the \(VIS\) band starts to trace near-UV to optical light, while all other bands still trace wavelengths redder than the 4000Å-break, and, indeed, quiescent galaxies have redder (\(VIS - Y\)) colours than star-forming objects. At \(2 < z < 3\) the separation is difficult again, as both the \(VIS\) and \(Y\) filters trace rest-frame \(\lambda < 4000\) Å, while the \(J\) and \(H\) filters trace rest-frame...
\[
\lambda > 4000 \text{ Å}. \text{ In Figure 1 the red line and open circles represent the observed wavelengths of the 4000Å-break at different redshifts and over Euclid’s wavelength coverage, to give an indication of which part of the SED is traced by each Euclid filter at different redshifts.}
\]

Similarly to the previous section, we define the area in \( VIS, Y, J, H \) colour-space used to select quiescent galaxies as:

\[
\begin{align*}
(VIS - Y) &> m (J - H) + q, \\
(VIS - Y) &> C_{\text{low}}, \text{ and} \\
(J - H) &< C_{\text{up}}.
\end{align*}
\]

(3)

Similar to the previous analysis, we derive the best line to separate quiescent and star-forming galaxies by maximising the quantity \( C(1 - FP) \), where \( C \) is the completeness and \( FP \) is the false-positive fraction.

A high false-positive fraction, above 30% at \( z < 0.5 \), and a low completeness, below 70% at \( z < 0.75 \), reflects the fact that quiescent galaxies are difficult to isolate at low redshifts. For this reason we exclude redshifts below 0.75 when analysing the redshift evolution of the selection area. Results for all six data sets are listed in Table 5.

We average the results of the mock galaxies of all the six data sets to obtain the evolution of the line separating star-forming and quiescent galaxies with redshift (Figure 12). In the Mice catalogue used for the Mice Wide and Mice Deep data sets, there are almost no quiescent galaxies at \( z > 1.25 \), but at lower redshift the line separation overall agrees with the value derived from the COSMOS2015 catalogue. As we did for the \((u - VIS)\) and \((VIS - J)\) colours, we adopt a sequential approach that starts from the fit of the slope-redshift evolution, and then uses the results of this fit to derive the redshift evolution of the intercept \( q \). The same method is then applied to the \((VIS - Y)\) limit and the \((J - H)\) limit. In the fit of the redshift evolution of each parameter we include marginalised errors obtained by considering all selection areas with \( C(1 - FP) > 0.983 \max[C(1 - FP)] \), which correspond to a maximum error of 10% in the \( C(1 - FP) \) value of any single data set. Differences in the marginalised error estimates with the \((u-VIS)\) vs. \((VIS-J)\) analysis are due to the different number of data sets considered. By combining the results of the different data sets, the line separating quiescent and star-forming galaxies can be described as a function of redshift as:

\[
\begin{align*}
m &= -1.59 z^2 + 3.66 z - 0.30, \\
q &= -0.33 z^2 + 1.61 z - 0.36, \\
C_{\text{low}} &= -1.34 z^2 + 4.20 z - 1.34, \\
C_{\text{up}} &= 0.74 z - 0.14.
\end{align*}
\]
We consider a second-degree polynomial for the slope \( m \), the intercept \( q \), and the \((V IS - Y)\) limit \((C_{\text{low}})\) and a linear regression for the \((J - H)\) limit \((C_{\text{up}})\). By considering higher-order polynomials the completeness and false-positive fractions at \(0.75 < z < 2.5\) do not change considerably. At the same time, considering lower-order polynomials decreases the average completeness below 50% and increases the average false-positive fractions above 50%.

As for the \((u - V IS)\) and \((V IS - J)\) colours, we verify the goodness of the selection criteria in all data sets by calculating completeness and false-positive fraction for the selection criteria using Equation 4 (Figure 13). We advice against extrapolating the selection criteria at \(z < 0.75\), as
the star-forming galaxies would have a high contamination in the selected sample. At z > 2 the combined effect of poor statistical constraints and the absence of colours that include the 4000Å-break makes the selection difficult. The best scenario for this case results in a low completeness and a very high false-positive fraction. However, relaxing the selection criterion mainly increases the false-positive fraction, rather than the completeness.

In Figure 13, we also show the completeness and false-positive fraction at different observed VIS magnitude, for galaxies at redshift 0.75 < z < 2. Differently from the results for the (u − VIS) and VIS − J) colours, the completeness for the (VIS − J) and (Y − H) colours shows a mild decrease with the observed VIS magnitude, with average values around 100% at VIS = 20 mag and around 70% at VIS = 26 mag. The false-positive fraction, on the other hand, shows an increase with the VIS observed magnitude, with the average values smaller than 50% only for objects between VIS = 21 mag and VIS = 24 mag. We do not find substantial differences between the Wide and Deep Surveys. Most differences arise from a variation in the data sets, particularly between the data sets derived from real galaxy observations (SED and Int data sets) and those from simulated galaxies (Mice data sets).

Overall, we conclude that (VIS − J) and (Y − H) colours can be used to select quiescent galaxies at 1 < z < 2 (0.75 < z < 2) with an average completeness above 65% (55%) and with false-positive fractions typically below ∼ 20%. Therefore, this colour combination is complementary in redshift to the (u − VIS) and (VIS − J) colour selection previously analysed and shows similar completeness, but a slightly larger false-positive fraction, i.e., below 15% at 0.25 < z < 1 for the (u − VIS) and (VIS − J) colours. In the future it is likely that morphology can be used in tandem with these colours to improve these selections.

5 SUMMARY

Colour-colour selections are widely used and well accepted methods in extragalactic astronomy to separate different galaxy population, such as quiescent and star-forming galax-

Table 5. Best selection criteria for the (VIS − Y) and (J − H) observed colours at different redshifts, as described in Equation 3. The last two columns report the completeness (C) and false-positive fraction (FP) of each selection.

<table>
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<th>data set</th>
<th>(C)</th>
<th>m</th>
<th>q</th>
<th>C_low</th>
<th>C_up</th>
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<td>0.6</td>
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</table>
ies. Given the limited number of filters in general and unusually wide visual filter in particular designed for the *Euclid* telescope, it is vital to determine a framework astronomers can use for this purpose. In this paper, we show that *Euclid* filters alone are not sufficient to pin down a best fit template to determine the rest-frame colours *U*, *V*, and *J* used in standard selections, as well as the sSFRs. We therefore derive *Euclid* specific selection criteria for the separation of quiescent and star-forming galaxies using *Euclid* observed colours.

To do so, we define three different sets of mock *Euclid* observations: i) the first interpolates the multi-wavelength observations of galaxies in the COSMOS2015 catalogue; ii) the second uses the best theoretical template describing the multi-wavelength observations of galaxies in the COSMOS2015 catalogue; iii) the third takes galaxy parameters from the Mice Simulation. Each data set contains mock observations for *Euclid*’s visible *VIS* filter, and the near-infrared filters NISP Y, J, and H. Data sets i) and ii) also include CFIS/u band observations. Similar u-band data will be available with other overlapping surveys such as LSST.

By selecting galaxy types in the commonly accepted *UVJ* plane derived from these mock observations, we only recover ~20% of the original quiescent galaxy population up to redshifts *z* = 3. The reason for this low success rate is the difficulty of deriving accurate (*U – V*) and (*V – J*) colours with only four filters as is the case for *Euclid*. Even worse, when we use the sSFR derived from the four *Euclid* filters to isolate quiescent galaxies, we recover only 9% of the original quiescent galaxy population. We find that the most effective way to separate quiescent from star-forming galaxies with observed colours is the combination of (*u – VIS*) and (*VIS – J*) colours. This filter combination will be available thanks to the *Euclid*-specific follow-up ancillary ground-based *u*-band observations. For this colour combination, the bulk of quiescent and star-forming galaxies (i.e., the areas containing 68% of the number density of these two classes of galaxies) are completely separated. We derive the quantitative separation of the two galaxy populations by maximising the completeness of the quiescent galaxy recovery and minimising the number of false-positive. We furthermore parameterise the evolution of this fitting with redshift. The proposed line allows for a selection of quiescent galaxies (with a recovery of more than 55% up to *z* ~ 1) while keeping the average fraction of false-positive below 15%. We find the highest success rates in the redshift range 0.25 < *z* < 1, where the completeness is above ~70%.

We also tested the performance of separating galaxy types while using only the four filters on board the *Euclid* telescope. Of the four colour combinations we tested, the (*VIS – Y*) and (*J – H*) colours are the most efficient for isolating quiescent galaxies. A drawback lies at lower redshifts: due to the absence of strong spectral features inside these filters at *z* < 0.75, quiescent and star-forming galaxies have similar colours at these low *z*. We therefore offer selection criteria only for higher redshifts. We do this by maximising the selection completeness and, at the same time, minimising the number of false-positive. The derived selection criteria allow the user to select a sample of quiescent galaxies at 0.75 < *z* < 2 with average completeness above 55%, and an average false-positive fraction below 20%. The selection works best in the redshift range 1 < *z* < 2, where we find a completeness above 65%.

The advantage of *Euclid* is that there is other information besides colours available, namely the resolved structure of galaxies up to high redshift. By using a combination of these colour and morphological techniques to remove asymmetric and clumpy galaxies it is likely that a higher success and lower contamination rate can be obtained. The addition
of spectroscopic information from the NISP spectra, when available, is also likely to improve the selection. This will be tested in future work.

ACKNOWLEDGEMENTS

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4 Observatoire Astronomique de Strasbourg (Observatoire Astronomique de Strasbourg, CNRS, UMR 7550, Strasbourg, France
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In this appendix we compare the relevant properties of galaxies in the different data sets considered in this work. Results are shown at Euclid Wide Survey depth.

Figure A1 shows the redshift, stellar mass, and sSFR distribution of the SED Wide Survey. The two data sets derived from real Euclid data sets have instead fainter magnitude distributions in the Euclid Wide Survey depth. The two data sets show similar galaxy properties, as expected given that they are derived from the same parent sample of real galaxies. These similarities overall reassure that the model and photometric errors assumptions done differently in the two samples are not influencing the results strongly. The Mice Wide data set is instead limited to galaxies at $z < 2$ with generally larger stellar mass and lower star-formation than the other two data sets. We verify that the difference visible in the stellar mass and sSFR distributions are not entirely caused by the difference in the redshift distributions and are indeed still present even focusing to low-redshift galaxies.

Figure A2 shows the magnitude distribution of galaxies in the Euclid filters for the three data sets with the depth of the Euclid Wide Survey. The two data sets derived from real galaxies, i.e., Sed Wide and Int Wide, have similar magnitude distributions in the Euclid filters. Mock galaxies in the Mice Wide data set have instead fainter VIS band magnitudes, as a possible consequence of galaxies being less star-forming in this data set. The magnitudes in the other Euclid filters are instead similar among the three different data sets.

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Figure A1. Distribution of redshift (left), stellar mass (center), and sSFR (right) for galaxies in the three different data sets considered in this work: SED Wide (filled orange histograms), Int Wide (green solid lines), and Mice Wide (blue dashed lines).

Figure A2. Distribution of magnitudes in the VIS (top left), J (top right), Y (bottom left), and H (bottom right) bands for galaxies in the three different data sets considered in this work: SED Wide (filled orange histograms), Int Wide (green solid lines), and Mice Wide (blue dashed lines). The vertical dotted lines indicate the magnitude corresponding to a S/N=3 for each filter.